

example, CRMS0136 freshened considerably in 2016. Salinity had a seasonal maximum greater than 5 ppt until 2016. The salinity then remained lower than 1.5 ppt until 2023 (Figure 1A). LAVegMod results over this time show an abrupt change in species composition at this grid cell (Figure 1B), while *in-situ* observations of vegetation composition at CRMS0136 show a more gradual transition (Figure 1C). With the increasing likelihood of faster transitions in the future decades, it is important to investigate transitions that have been observed and explore alternatives to the niche-approach to vegetation modeling, such as identifying successional patterns and trajectories.

Project Objectives and Methods: The graduate student will utilize the data collected through CRMS to identify vegetation transition patterns. CRMS stations were established in 2006-2007, producing over 18 years of annual vegetation surveys, timeseries of environmental conditions (e.g., water level, salinity, precipitation, temperature), and regular measurement vegetation and soil properties (e.g., above and belowground biomass, accretion, bulk density).

We leverage the work by Snedden (2019) to reduce the complexity of available data. Snedden (2019) trained a self-organizing map (SOM) with the available CRMS data, producing 260 map units that were further classified into 11 vegetation community types (VCT). Rather than having states defined by the percent cover of each species in the surveyed CRMS plots, the student will use the VCT and 260 map units to define each plot through time and will create a framework for tracking transitions through time. Two additional states will be added, unvegetated ground (i.e., bareground) and open water, to account for land building and land loss observed at the sites.

Although land building is not currently observed at CRMS sites since all are established within the vegetated wetlands, including that state is important, as it gives the method greater flexibility for future use. Figure 2 A and B show the difference between transitioning between the VCTs (A) and between the map units (B). The VCT data is readily available, and the map units can be calculated from the survey data. Python code for determining the best matching unit (BMU) for LAVegMod results is available on Github (Foster-Martinez, <https://github.com/CPRA-MP>) and can be adjusted to work with CRMS survey input.

Via sequential encoding and a transition matrix, the frequency of transitioning between states will be tracked, allowing for the probabilities of common transitions to be calculated. Perhaps equally as important, trajectories that do not occur will be identified. By grounding the analysis in CRMS observations, ecological functions can influence the results,

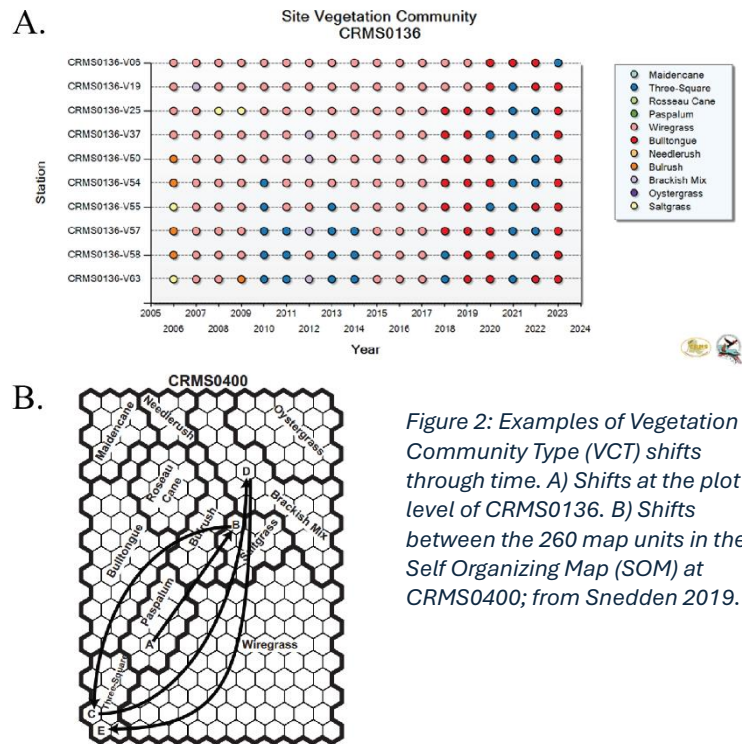


Figure 2: Examples of Vegetation Community Type (VCT) shifts through time. A) Shifts at the plot level of CRMS0136. B) Shifts between the 260 map units in the Self Organizing Map (SOM) at CRMS0400; from Snedden 2019.

What comes next? Tracking wetland transitions across the Louisiana coast

even if they are not explicitly represented in a mechanistic model. For example, Turner et al. (2004) showed that with healthy below ground biomass, marshes can recover, even if aboveground biomass is reduced. That could manifest in survey data as more consistent vegetation coverage.